Binary Integration Performance Analysis of CA Family of CFAR Strategies in Homogeneous Weibull Clutter

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Abstract—The exact knowledge of the clutter properties is of great importance for modern radar systems due to the role that they are directly play mainly through the CFAR processor design in the optimization of the detection process. Owing to the central limit theorem, the most used models are of Gaussian distribution that has the feature of simple processing architectures. Actually, these models are expected to represent, to a good extent, the sea and terrain clutters for poor-resolution and largely grazing angle radar. If any of these two practical situations is no longer satisfied, these models become insufficient for the clutter representation. Under these circumstances, the clutter becomes spikier and this successively leads to a false alarm rate behavior, which is much more important than that predicted by a Gaussian model. For that reason, other models, which are capable of taking into account these types of operating conditions, have to be investigated. This is typically needed for the case of high-resolution radars. The developed clutter models will allow us to reduce the intensity of clutter, through the reduction of the analyzed cell resolution and, consequently, the signal-to-noise ratio will be improved. Accordingly, the target detection probability should increase. Weibull represents one of the most suitable distributions for the high-resolution land clutter modeling. On the other hand, due to the simplicity of binary integrator and its robustness in non-Gaussian clutter, it has been widely used in radar detectors. This paper is interested in evaluating the detection performance of the CA (Cell-Averaging) family of CFAR schemes against clutter of Weibull distribution, with an assumption of known shape parameter, when they incorporate a binary integrator amongst their basic contents.

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1. INTRODUCTION

The radar key features are its ability to detect objects at long distances or in conditions of poor visibility. These characteristics are of particular importance for safe navigation and collision avoidance of aircrafts and ships. Therefore, radar is a vital equipment that is employed for scanning a natural environment and detecting physical objects that it may contain.

Its tool is the transmission of electromagnetic waves, which are used to illuminate the space location of interested and to record the reflections. The reflected echoes from the objects are received and processed before they are displayed to the user. In the illuminated environment, numerous objects may introduce reflections and scattering of the transmitted radar signal causing difficulties in detecting objects of interest. From the detection point of view, objects of interested are termed as targets, while the interfering echoes are designated as clutter [1-5].

The automatic detection of a target in a non-stationary noise and clutter background while maintaining a constant probability of false alarm represents the main task of a radar system. In this regard, detection involves comparing the linear or square-law detected signal to a threshold and showing if the signal magnitude succeeds or fails in crossing this threshold to declare whether or not the target is present.

Due to the non-stationary nature of the background noise, the classical detection based on a matched filter receiver followed by a fixed threshold is incapable to implement the goal of fixing the false alarm rate. One approach to solving this problem is to replace the fixed threshold with a varying threshold. The new threshold is updated according to the intensity variation of the environmental clutter in such a way that it adapts its value to follow this variation. Therefore, the adaptive threshold technique is regarded as the best solution to meet the request of keeping the false alarm rate unchanged.

ADDITIONAL INFORMATION

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