

# Adaptive Algorithm of Maneuvering Target Tracking in Complex Jamming Situation for Multifunctional Radar with Phased Antenna Array

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**Abstract**—Adaptive multimodel algorithms based on the target movement model in the form of discrete stochastic dynamic system with random structure are adequate to the problem of target tracking based on data of the multifunctional radar station (MFRS) with phased antenna array (PAA) under conditions of complex dynamically varying signal and jamming situation. This study presents an optimal and quasioptimal algorithms of adaptive estimation of movement parameters of maneuvering targets in the Cartesian coordinate system for MFRS with PAA based on the mathematical tools of mixed Markov processes in discrete time. They describe the evolution of joint a posteriori probability density of the vector of target movement parameters and switching variable determining the mode of its movement, while the filters implementing them are referred to the class of devices with feedbacks between channels. The identification of blips in the tracking strobe is performed in the spherical coordinate system by selecting the blip, which is the closest to the strobe center. The efficiency analysis of the developed tracking algorithm is performed by using the test paths of two targets with different intensities of the maneuver and parameters of tracking modes. The accuracy characteristics of adaptive filter and indicators of the tracking efficiency at different false alarm probabilities have been determined.

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## INTRODUCTION

Modern multifunctional radar stations (MFRS) are forced to operate in complex dynamically varying signal and jamming situation stipulated by the presence of a large number of different targets of various kinds that differ in their speed, height, and maneuvering characteristics and also by the presence of interferences of natural and artificial origin [1–3].

The following possibilities are available in solving functional problems in MFRS with two-dimensional phased antenna array (PAA) [4, 5]:

- infinitely fast control by the beam of antenna array pattern in space during the search and tracking of targets;
- control of radiation energy in the fixed direction, where the beam of antenna directivity diagram is located.

Such possibilities of MFRS with PAA make it possible to simultaneously carry out several tasks:

- space surveillance;
- starting of paths of detected targets;
- path tracking.

Owing to the specified properties, the effective solution of the above tasks in complex operating conditions is ensured at the expense of operation in the mode of time and energy division between the main functional tasks: search, lock-on, and tracking of targets. Practical implementation of the principle of time and energy division is performed by using the methods of adaptive dynamic control by the space scanning program [6, 7].

#### CONFLICT OF INTEREST

The authors declare that they have no conflict of interest.

#### ADDITIONAL INFORMATION

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