

Adaptive Filtration of Radio Source Movement Parameters Based on Sensor Network TDOA Measurements in Presence of Anomalous Measurements

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Received April 25, 2018

Revised January 14, 2019

Accepted January 24, 2019

Abstract—The methods based on TDOA measurements find wide application for localization of radio sources using wireless sensor networks. The need of taking into account the presence of anomalous measurement results often occurs in real conditions. Their appearance means a significant malfunction of sensor network components that results in divergence of traditional algorithms of Kalman filtration of radio source movement parameters. Based on the mathematical tools of mixed Markov processes in discrete time domain, the optimal and quasioptimal algorithms of adaptive filtration of radio source movement parameters were synthesized on the basis of TDOA measurements of sensor network in the presence of anomalous measurements. The optimal algorithm describes the evolution of joint a posteriori probability density of the vector of movement parameters and switching variables determining the type of measurement errors of network sensors. The quasioptimal algorithm obtained by linearization of the measurement equation involves the implementation of sequential technique of incoming data processing and performance of the Gaussian approximation of a posteriori probability density of radio source movement parameters. For the case considered in this paper using the statistical simulation, the developed quasioptimal algorithm makes it possible to recognize the appearance of anomalous errors of measurements with probability close to unity and eliminate their impact on the accuracy of determining the radio source movement parameters.

DOI: 10.3103/S073527271902002X

INTRODUCTION

The problem of passive localization of radio emission sources (RAS) is quite common in the field of environment monitoring, liquidation of aftermaths of natural disasters, in intelligent transport and security systems [1–3]. The RAS location can be determined by using wireless sensor networks (WSN) [4–7] that became an important field of research in recent years.

WSN have started to be actively applied in different fields, such as emergency relief operations, autonomous supervision and monitoring of industrial processes and the environment (monitoring of wild animals), monitoring and control of mobile objects, etc. In performing the emergency relief operations, WSN ensure the possibility of position-finding of members of rescue teams (e.g., fire-fighting team), and also technical equipment (e.g., robots), that makes easier the attainment of target goals. An important feature of WSN is the possibility of tracking mobile objects (targets).

One of the main approaches to passive localization of RAS is based on using TDOA measurements containing information about the time difference of arrival of signals obtained by different sensors and the WSN reference sensor. In his case, the synchronization of RAS and WSN sensors is not required making it possible to apply this approach to the localization of unknown targets [8–13].

The accuracy of determining RAS coordinates on the basis of TDOA measurements depends on measurement errors of the time of signal reception by the sensor network transducers. It is known [14] that under real conditions the need often arises to take into account along with ordinary (normal) measurement results the presence of anomalous (rough) measurements. The measurements with anomalous errors can be

CONFLICT OF INTEREST

The authors declare that they have no conflict of interest.

ADDITIONAL INFORMATION

The initial version of this paper in Russian is published in the journal “Izvestiya Vysshikh Uchebnykh Zavedenii. Radioelektronika,” ISSN 2307-6011 (Online), ISSN 0021-3470 (Print) on the link <http://radio.kpi.ua/article/view/S002134701902002X> with DOI: [10.20535/S002134701902002X](https://doi.org/10.20535/S002134701902002X).

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